

GOES-16 NRT Fire Detection on OpenNEX

Spectral Bands



Full-Disk Views





Solar Zenith Angles





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The NASA Earth eXchange (NEX)

The NASA Earth eXchange (NEX, <u>https://nex.nasa.gov</u>) provides a collaboration and knowledge-sharing platform for the Earth science community housed at Ames Research Center.

OpenNEX is part of NEX as its public cloud infrastructure portal, hosted on the Amazon Web Services (AWS) cloud for public accessibility.

Over the past five years, NEX team supported over 100 NASA-funded researchers.





Himawari 8 AHI and GOES-16 ABI



Himawari 8 AHI fullDisk launched October 7, 2014 Himawari 9: November 2, 2016

	Himawari-8/9					
Wave length [µm]	Band number	Spatial resolution at SSP [km]	Central wave length [µm]			
			AHI-8 (Himawari-8)	AHI-9 (Himawari-9)		
0.47	1	1	0.47063	0.47059		
0.51	2	1	0.51000	0.50993		
0.64	3	0.5	0.63914	0.63972		
0.86	4	1	0.85670	0.85668		
1.6	5	2	1.6101	1.6065		
2.3	6	2	2.2568	2.2570		
3.9	7	2	3.8853	3.8289		
6.2	8	2	6.2429	6.2479		
6.9	9	2	6.9410	6.9555		
7.3	10	2	7.3467	7.3437		
8.6	11	2	8.5926	8.5936		
9.6	12	2	9.6372	9.6274		
10.4	13	2	10.4073	10.4074		
11.2	14	2	11.2395	11.2080		
12.4	15	2	12.3806	12.3648		
13.3	16	2	13.2807	13.3107		



GOES-16 ABI fullDisk launched November 19, 2016 GOES-17 March 1, 2018 TABLE 1. Summary of the wavelengths, resolution, and sample use and heritage ins bands. The minimum and maximum wavelength range represent the full width at or 50%) points. [The Instantaneous Geometric Field Of View (IGFOV).]

	Future GOES imager (ABI) band	Wavelength range (µm)	Central wavelength (µm)	Nominal subsatellite IGFOV (km)	Sample use
	I	0.450.49	0.47	I.	Daytime aerosol over land, coastal water mapping
	2	0.59-0.69	0.64	0.5	Daytime clouds fog, inso lation, winds
	3	0.8460.885	0.865	T	Daytime vegetation/burn scar and aerosol over water, winds
	4	1.371-1.386	1.378	2	Daytime cirrus cloud
	5	1.58-1.64	1.61	1	Daytime cloud-top phase and particle size, snow
	6	2.225-2.275	2.25	2	Daytime land/cloud properties, particle size, vegetation, snow
	7	3.80-4.00	3.90	2	Surface and cloud, fog at night, fire, winds
	8	5.776.6	6.19	2	High-level atmospheric water vapor, winds, rainfall
	9	6.75-7.15	6.95	2	Midlevel atmospheric water vapor, winds, rainfall
	10	7.24-7.44	7.34	2	Lower-level water vapor winds, and SO ₂
	Ш	8.3-8.7	8.5	2	Total water for stability, cloud phase, dust, SO ₂ rainfall
	12	9.42-9.8	9.61	2	Total ozone, turbulence, and winds
	13	10.1-10.6	10.35	2	Surface and cloud
	14	10.8-11.6	11.2	2	Imagery, SST, clouds, rainfall
	15	11.8-12.8	12.3	2	Total water, ash, and SST
	16	13.0-13.6	13.3	2	Air temperature, cloud heights and amounts



GEONEX Real Time Pipeline





How will the GOES ABI characterize fires?

Fire properties can be characterized in three ways: instantaneous fire size, instantaneous fire temperature and fire radiative power (FRP).

Fires produce a stronger signal in the midwave IR bands (around 4 microns) than they do in the longwave IR bands (such as 11 microns). That differential response forms the basis for most Fire Detection and Characterization (FDC) algorithms, including the algorithm used for GOES. FDC was taken into account when creating the specifications of the 3.9 micron band on ABI, allowing GOES-16 to exceed the FDC performance seen with previous GOES satellite sensors.





Wildfire Detection Algorithm (AHI-FSA)





Article

Development of a Multi-Spatial Resolution Approach to the Surveillance of Active Fire Lines Using Himawari-8

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Archived Fire-event dataset for Machine Learning



California Statewide Fire Map http://www.fire.ca.gov/general/firemaps



La Tuna Fire, Verdugo Mountains Los Angeles, CA, Sep 1st - Sep 7th, 2017



NEX-MATA Intelligent assistants

NEX-MATA is an integration of the Speech Recognition (SR), Natural Language Processing (NLP), and Machine Learning (ML) into an intelligent assistant, helping Earth scientists and citizens access the GOES fire database in a conversation-like interface.







Summary

• Real-time GOES-16 data can improve the timeliness of fire behavioral data.

Thank You!

- GEONEX has laid the groundwork for real-time wildfire monitoring on a public cloud.
- Using the denser temporal data available from GOES to track the status of pixels such as non-fire, fire, and burnt area, could reduce false detection rates seen from polar-orbiting data sources.

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GEONEX Real Time Pipeline

- 1. GEONEX is a real-time pipeline deployed on OpenNEX to process geostationary datasets such as those from GOES-16 and Himawari into higher level products. Planned products include TOA, SR, LAI, NDVI, GPP and Fire.
- The real-time feed and full historical archive of original resolution Advanced Baseline Imager (ABI) radiance data (Level 1b) and full resolution Cloud and Moisture Imager (CMI) products (Level 2) are added into AWS as soon as they're available (netCDF4 format).
- 3. GEONEX, a real-time pipeline prototype to convert ABI data from radiance data into top-of-the atmosphere (TOA) reflectance and surface reflectance (SR) outputs for advanced detection. Himawari-8 (AHI) data were processed following similar steps.
- 4. GEONEX is designed as a real-time processing chain, deployed both on the AWS cloud as well as on the NAS supercomputer at NASA Ames.



WF-ABBA (CIMSS)



Remote Sensing of Environment Volume 127, December 2012, Pages 194-209



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On timeliness and accuracy of wildfire detection by the GOES WF-ABBA algorithm over California during the 2006 fire season Alexander Kollunov * A ^{ca}, Susan L, Uslin *, Elaine M, Prins *

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Abstract

The Wildfire Automated Biomass Burning Algorithm (WF-ABBA) is a state-of-the-art algorithm for geostationary wildfire detection whose results have been increasingly used in a range of environmental applications. At present, the WF-ABBA validation activities and, in general, fire product validation methodologies are at a markedly less advanced stage than the algorithm itself. Particularly, little is known about detection timeliness, despite the value of such information for assessing the potential of geostationary observations to improve tactical decision making of first responders. This paper contributes to reducing this gap in two ways. Firstly, we describe a new methodology that is suitable for evaluating geostationary satellite wildfire detection in terms of incidents with regard to both timeliness and reliability. This methodology utilizes available official multi-agency wildfire reporting information and multitemporal Landsat imagery. Secondly, we apply the proposed validation method to temporally filtered GOES-West WF-ABBA (ver. 6.1) detections for the 2006 fire season over the State of California and present incident-wise and pixel-wise performance information. The results indicate highly reliable pixel-wise performance of WF-ABBA, with about 75% of fire pixels (or more) corresponding to actual recorded active wildfires. A substantial portion of wildfires were detected during their first hour of activity, and a few incidents-even before the initial reports from conventional sources. Although the WF-ABBA performs best at what it was designed for: consistently re-detecting (monitoring) active fires, we believe there is an additional potential for automated detection from current geostationary data to reduce wildfire ignition latencies in the Western U.S. Our results can serve as a guideline for algorithm developers and users of the WF-ABBA fire product

